

Description

The SiT92317 family of parts are HCSL Low-Power (HCSL-LP), 6 output differential Fan-Out buffers that meet or exceed all the performance requirements of the Intel DB800Z specification. They are suitable for PCI Express Gen1–7 or QPI/UPI applications.

The SMBus interface and multiple output-enable pins allow the configuration and control of all 6 outputs individually.

It is packaged in a compact VQFN package and uses a standard pin configuration.

Applications

- Micro server and tower server
- Rack server
- Storage area network (SAN) and host bus adapter (HBA) card
- Network attached storage (NAS)
- Hardware accelerator

Features

- HCSL-LP outputs with $Z_o = 85\ \Omega$ or $100\ \Omega$ output impedance options
- Saves power and board space – no termination resistors required
- Supports PCIe and QPI applications
- Spread spectrum compatible; tracks spreading input clock for low EMI
- Additive phase jitter
 - $F_{clk} = 156.25\ \text{MHz}$ (12k-20M) band $\sim 32\ \text{fs}$ (Typical)
 - $F_{clk} = 100\ \text{MHz}$
 - PCIe Gen5 (CC) filter (CC) $\sim 13\ \text{fs RMS}$
 - PCIe Gen6 filter (CC) $\sim 8\ \text{fs RMS}$
 - PCIe Gen7 filter (CC) $\sim 6\ \text{fs RMS}$
- Programmable output slew rate control
- 3.3 V core and IO supply voltages
- Hardware-controlled low power mode (PDN)
- Current consumption: 48 mA Typical with all 6 outputs enabled at 100 MHz, driving a 10 inch T line and 2 pF load on each output

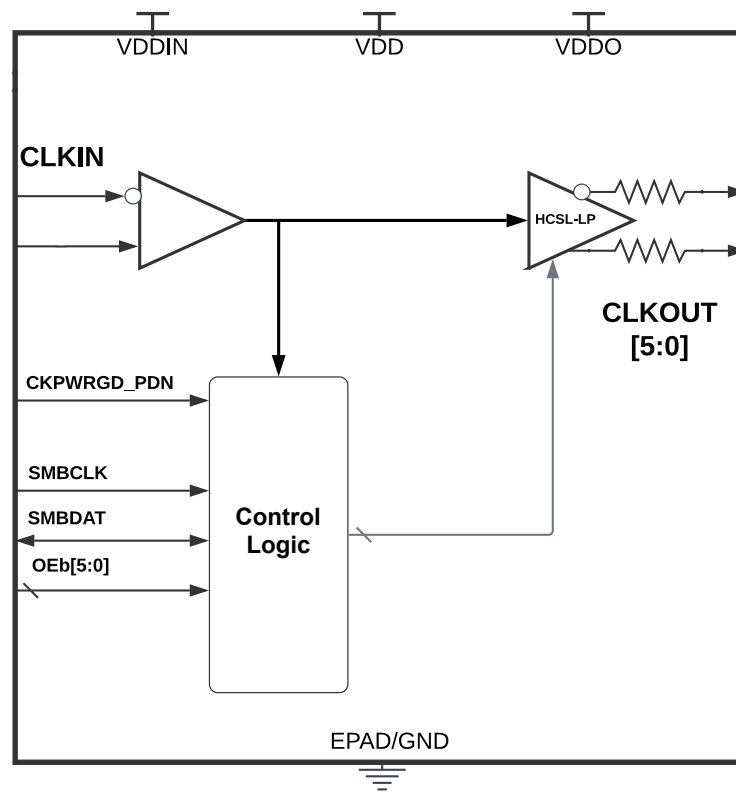


Figure 1. SiT92317 Functional Overview

Table of Contents

Description 1

Applications 1

Features..... 1

Ordering Information..... 3

Electrical Characteristics..... 4

Pin Description..... 8

Functional Description 10

 Typical Application 10

 Parameter Measurement Information..... 10

 Power Good Assertion and De-assertion 12

 Power Good De-Assertion..... 12

 Power Good Assertion 12

Generic SMBus Description 14

 SMBus Byte: Read and Write Operations 15

 Byte Read 15

 Byte Write..... 15

 SMBus Block: Read and Write Operations..... 16

 Block Read..... 16

 Block Write 17

 SMBus Address 17

Register Address 18

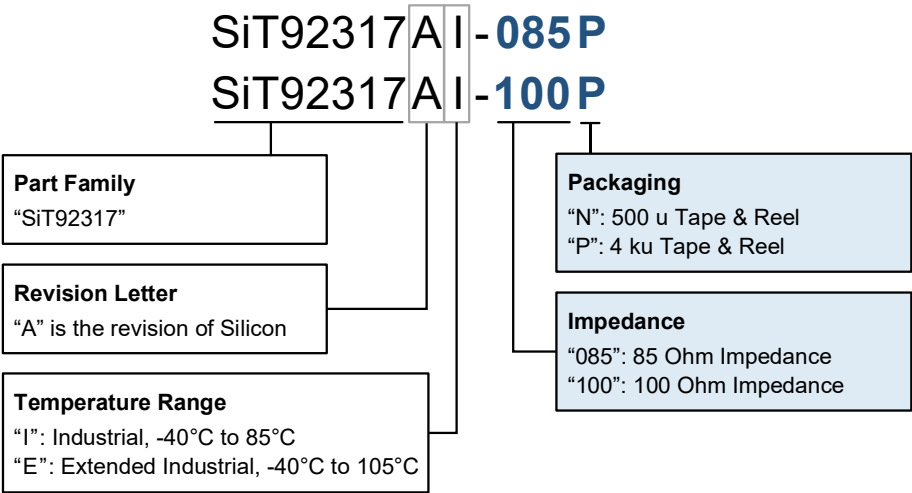
Package Dimensions and Patterns..... 19

 Land Pattern and Solder Paste Design 20

 Top Marking 21

Revision History..... 22

Ordering Information



Electrical Characteristics

Table 1. Absolute Maximum Ratings

Parameter	Conditions	Symbol	Min	Typ	Max	Units
Supply Voltage	Input Supply Core Supply	VDDIN VDD			3.63	V
Output Bank Supply Voltage	Output Driver Supply	VDDO			3.63	V
Input Low Voltage		V _{IL}	GND-0.5			V
Input High Voltage	Except for SMBus interface	V _{IH}			VDD+0.5	V
Input High Voltage	SMBus clock and data pins	V _{IHSMB}			3.6	V
Storage Temperature		T _s	-65		150	°C
Junction Temperature		T _j			125	°C
ESD (Human Body Model)	JESD22A-114	ESDHBM			2000	V
ESD(Charge Device Model)		ESDCDM			500	V
Latch Up	JEDEC JESD78D	LU			100	mA
Moisture Sensitivity Level		MSL		3		

Notes:

- Exceeding maximum ratings may shorten the useful life of the device.
- Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or at any other conditions beyond those indicated under the DC Electrical Characteristics is not implied. Exposure to Absolute-Maximum-Rated conditions for extended periods may affect device reliability or cause permanent device damage.

Table 2. Recommended Operating Supply and Temperature

Parameter	Conditions	Symbol	Min	Typ	Max	Units
Input Supply Voltage		VDDIN	2.97	3.3	3.465	V
Core Supply Voltage		VDD	2.97	3.3	3.465	V
Output Supply Voltage		VDDO	2.97	3.3	3.465	V
Ambient Temperature	Industrial (I)	T _A	-40		85	°C
	Extended industrial (E)		-40		105	°C
Junction Temperature		T _J			125	°C

Table 3. Electrical Characteristics

Parameter	Conditions	Symbol	Min	Typ	Max	Units
Operating Supply Current, CKPWRGD High ^[1,2]	Input Supply Current, No Clock	IDD _{VDDIN_STATIC}		7.3	9.5	mA
	Input Supply Current, 100 MHz Clock	IDD _{VDDIN_DYN}		7.4	9.5	mA
	Core Supply Current, No Clock	IDD _{VDD_STATIC}		5.7	9.5	mA
	Core Supply Current, 100M Clock (Industrial (I))	IDD _{VDD_DYN}		9.3	16	mA
	(Extended industrial (E))			9.3	18	mA
Output Supply Current, CKPWRGD High ^[1]	Output Supply Current, No Clock	IDD _{VDDO_STATIC}		6.6	8	mA
	All Outputs Enabled, driving a 10in T-line terminated with 2 pF cap at 100 MHz clock, SiT92316AIP	IDD _{VDDO_DYN}		48	75	mA
	SiT92316AI100P			44	68	
Power Down Current ^[1,2]	CKPWRGD = Low	IDD _{VDDIN_PDN}		0.023	0.1	mA
		IDD _{VDD_PDN}		3.5	5	mA
		IDD _{VDDO_PDN}		0.44	1.25	mA
Input Control Pin Characteristics						
Input high voltage – Logic inputs ^[2]		V _{IH}	0.7xVDD			V
Input low voltage – Logic inputs ^[2]		V _{IL}			0.3xVDD	V

Parameter	Conditions	Symbol	Min	Typ	Max	Units
Pin Inductance ^[3]		L_{PIN}			2	nH
Capacitance ^[3]	Logic Inputs, except DIF_IN	C_{IN}			4.5	pF
	DIF_IN differential clock inputs	C_{INDIF_IN}			2.7	
	Output pin capacitance	C_{OUT}			4.5	

Notes:

1. Guaranteed by characterization.
2. Guaranteed by production testing.
3. Guaranteed by design.

Table 4. Input Clock Characteristics

Unless otherwise specified: VDDIN = 3.3 V $\pm$ 5%, VDDO = 3.3 V $\pm$ 5%, -40°C $\leq$ TA $\leq$ 85°C, CLKIn driven differentially.

Parameter	Conditions	Symbol	Min	Typ	Max	Unit
Input frequency range		F_{CLKIn}	1		400M	Hz
Peak differential input voltage swing		VID	0.1			V
Input Slew Rate - CLK _{IN}	Measured differentially	dv/dt	0.2		4	V/ns
Input Leakage Current	VIN = VDD, VIN = GND	I_{IN}	-5		5	μ A
Input Duty Cycle	Measurement from differential waveform	d_{TIN}		50		%
Input Crossover Voltage	Crossover voltage		0.1		0.9	V

Table 5. Output Clock Characteristics (HCSL-LP) at 100 MHz

T_A = T_{COM}; Supply Voltage VDDO = 3.3 V $\pm$ 5%

Parameter	Conditions	Symbol	Min	Typ	Max	Units
Slew rate ^{[1][5][6]}	Scope averaging on	Trf	2.4	2.9	3.5	V/ns
Slew rate matching ^[1]	Slew rate matching, Scope averaging on	ΔTrf			18	%
Voltage High ^{[1][5][6]}	Statistical measurement on single-ended signal using oscilloscope math function. (Scope averaging on) (Industrial (I))	V_{High}	721	794	868	mV
	(Extended industrial (E))	V_{High}	721	794	870	mV
Voltage Low ^{[1][5]}	Statistical measurement on single-ended signal using oscilloscope math function. (Scope averaging on)	V_{Low}	-86	11	84	mV
Max Voltage ^{[1][5][6]}	Measurement on single ended signal using absolute value. (Scope averaging off) (Industrial (I))	V_{max}	811	856	890	mV
Min Voltage ^{[1][5]}	(Extended industrial (E))	V_{min}	-119	-49	22	
		V_{min}	-119	-49	32	
Vswing ^{[1][5][6]}	Scope averaging off [pk to pk, single ended]	V_{SWING}	841	905	973	mV
Crossing Voltage (abs) ^[1]	Scope averaging off	V_{cross_abs}	380	423	455	mV
Crossing Voltage (var) ^[1]	Scope averaging off	ΔV_{cross}	-19	27	71	mV
Differential Impedance ^[2]	SiT92317AIP	Z_{DIFF}	80	85	90	Ω
	SiT92317AI100P		94	100	106	Ω
Clock Stabilization ^[3,4]	From VDDO power-up and after input clock stabilization or assertion of CKPWRGD to 1st Clock	T_{STAB}		1.0	1.8	ms
OEB Latency ^[3,4]	DIF starts after OEB assertion DIF stop after OEB de-assertion	t_{LATOEB}	4		6	Clocks
Tdrive_PDb ^[3,4]	DIF output enable after CKPWRGD assertion	t_{DRVpDb}		100	300	μ s

Notes:

1. Guaranteed by characterization, measured on 10 inch T-line with 2pf load.
2. Guaranteed by production testing.
3. Control input must be monotonic from 20% to 80% of input swing.
4. Guaranteed by limited testing of typical parts.
5. Default factory configuration.
6. The cpk = 1.33.

Table 6. SMBus Electrical Parameters

$T_A = T_{AMB}$. Supply voltages are per normal conditions. See Test loads for loading conditions.

Parameter	Conditions	Symbol	Min	Typ	Max	Units
SMBus Input Low Voltage ^[1]		V_{ILSMB}			$0.3 \times VDD$	V
SMBus Input High Voltage ^[1]		V_{IHSMB}	$0.7 \times VDD$		VDD	V
Hysteresis on SMBUS pins		V_{HYS}	0.048			V
SMBus Output Voltage ^[1]	$I_{OH} = -2 \text{ mA}$	V_{OHSMB}	$0.75 \times VDD$			V
	$I_{OL} = 2 \text{ mA}$	V_{OLSMB}			$0.25 \times VDD$	V
SMBus Operating Frequency ^[1]		f_{SMB}	4		400	kHz
Max Capacitive Load for Each Bus line		C_B		400		pf

Notes:

1. Guaranteed by characterization.

Table 7. Skew and Differential Jitter Parameters

Parameter	Conditions	Symbol	Min	Typ	Max	Units
CLK IN _x , CLKOUT _x ^[1,2,4,5,6,7,9]	Input-to-Output Skew in nominal value @ 25°C, 3.3 V (Industrial (I))	t_{PD}	455	600	723	ps
	(Extended industrial (E))	t_{PD}	411	600	744	ps
CLKIN _x , CLKOUT _x ^[1,2,6,7,8]	Input-to-Output Skew Variation across temperature	T_{PD_DRIFT}		0.4	0.82	ps/C
DIF ^[1,2,5,6,7,9]	Output-to-Output Skew across all outputs(Industrial (I))	t_{SKEW_ALL}			50	ps
	(Extended industrial (E))	t_{SKEW_ALL}			50	ps
DIF Skew	Output to output skew variation across temp				0.07	ps/C
Duty Cycle Distortion ^[1,3,5,6]	Measured differentially, @100MHz	t_{DCD}	-1	0.1	1	%

Notes:

1. Guaranteed by characterization.
2. Differential cross-point to differential cross-point measurement.
3. The difference in Duty Cycle between the output and input clock is referred as Duty Cycle Distortion.
4. Mean Value measured through scope averaging.
5. Measured from differential waveform.
6. Measured into fixed 2pF load cap. Input to output skew is measured at the first output edge following the corresponding input.
7. All input-to-output specs refer to the timing between an input edge and the specific output edge created by it.
8. This is the amount of input-to-output delay variation with respect to temperature.
9. The cpk = 1.33.

Table 8. Phase Jitter Parameters-PCIe Common Clocked (CC) Architecture

Parameters	Conditions	Symbol	Min	Typ	Max	Units
Additive Phase Jitter Common Clock	PCIe Gen 1 HF ^[1,2,3,4]	$t_{jphPCIeG1-CC}$		1.9	4.7	ps (p-p)
	PCIe Gen 2 HF ^[1,2,3,4,5,6]	$t_{jphPCIeG2-CC}$		102	138.4	fs rms
	PCIe Gen 2 LF ^[1,2,3,4,5,6]	$t_{jphPCIeG2-CC}$		4	7.7	fs rms
	PCIe Gen 3 ^[1,2,3,4,5,6]	$t_{jphPCIeG3-CC}$		33	44.3	fs rms
	PCIe Gen4 ^[1,2,3,4,5,6]	$t_{jphPCIeG4-CC}$		33	44.3	fs rms
	PCIe Gen5 ^[1,2,3,4,5,6]	$t_{jphPCIeG5-CC}$		13	17.5	fs rms
	PCIe Gen6 ^[1,2,3,4,5,6]	$t_{jphPCIeG6-CC}$		8	10.6	fs rms
	PCIe Gen7 ^[1,2,3,4,5,6]	$t_{jphPCIeG7-CC}$		5	7.4	fs rms
Additive Phase Jitter SRIS	PCIe Gen 2 HF ^[1,2,3,4,5,6]	$t_{jphPCIeG2-SRIS}$		70	122.7	fs rms
	PCIe Gen 2 LF ^[1,2,3,4,5,6]	$t_{jphPCIeG2-SRIS}$		18	2.8	fs rms
	PCIe Gen 3 ^[1,2,3,4,5,6]	$t_{jphPCIeG3-SRIS}$		29	53.7	fs rms
	PCIe Gen4 ^[1,2,3,4,5,6]	$t_{jphPCIeG4-SRIS}$		30	55.3	fs rms
	PCIe Gen5 ^[1,2,3,4,5,6]	$t_{jphPCIeG5-SRIS}$		10	17.1	fs rms
	PCIe Gen6 ^[1,2,3,4,5,6]	$t_{jphPCIeG6-SRIS}$		7	11.0	fs rms
	PCIe Gen7 ^[1,2,3,4,5,6]	$t_{jphPCIeG7-SRIS}$		4	8.7	fs rms

Parameters	Conditions	Symbol	Min	Typ	Max	Units
Additive Phase Jitter SRNS	PCIe Gen 2 HF ^[1,2,3,4,5,6]	tjph _{PCIeG2-SRNS}		68	110.2	fs rms
	PCIe Gen 2 LF ^[1,2,3,4,5,6]	tjph _{PCIeG2-SRNS}		1	1.3	fs rms
	PCIe Gen 3 ^[1,2,3,4,5,6]	tjph _{PCIeG3-SRNS}		24	36.2	fs rms
	PCIe Gen4 ^[1,2,3,4,5,6]	tjph _{PCIeG4-SRNS}		24	36.2	fs rms
	PCIe Gen5 ^[1,2,3,4,5,6]	tjph _{PCIeG5-SRNS}		9	13.2	fs rms
	PCIe Gen6 ^[1,2,3,4,5,6]	tjph _{PCIeG6-SRNS}		6	9.7	fs rms
	PCIe Gen7 ^[1,2,3,4,5,6]	tjph _{PCIeG7-SRNS}		4	6.8	fs rms

Notes:

1. Guaranteed by design and characterization. Applies to all differential outputs.
2. Input to SiT92317 is fed using low phase noise source SMA100B while SiT92317 is configured as 100 MHz LP-HCSL Output Driver and fed to the channels of the DSO through low noise high slew drivers to minimize the impact of DSO broadband noise.
3. Additive RMS Jitter Measurement for PCIe are made using DSO. Commercially available and popular PCIe jitter post processing tools are used to report PCIe jitter.
4. Additive jitter for RMS values is calculated by solving the equation for b [$b = \sqrt{(c^2 - a^2)}$] where 'a' is the rms input jitter and "c" is the rms total jitter.
5. Input to SiT92317 is fed using low phase noise source SMA100B, SiT92317 is configured as 100MHz HCSL Output Driver [VDDOx = 3.3 V] and fed to the channels of DSA90804A using the exact measurement set up.
6. For each type of PCIE jitter – Common Clock, SRIS, SRNS, there are 64 possible PCIE GEN filter values. We take the worst case jitter value over process, voltage and temperature among these 64 filters. The spec of H1, H2 (TX, RX PLL transfer functions) are F3dB = [2,4,5] MHz, Peaking = [0.01, 1, 2] dB, For H3 filter F3dB=[10] MHz.

Table 9. Phase Jitter Parameters

Parameters	Conditions	Symbol	Min	Typ	Max	Unit
Additive Phase Jitter, 12K-20M	Fin = 156.25M (Industrial (I))	tjph_12K_20M		32	42.0	fs rms
	Fin = 156.25M (Extended Industrial (E))				44.0	
Additive Jitter with BRMC Filter⁽¹⁾	Fin = 312.5 MHz (Industrial (I))	tjph _{BMRC}		20	28.5	fs rms
	Fin = 312.5 MHz (Extended Industrial (E))				30.0	

Notes:

1. 4 MHz 1st order HPF, 20 MHz Brick-Wall Low-Pass filter, no Aliasing.

Pin Description

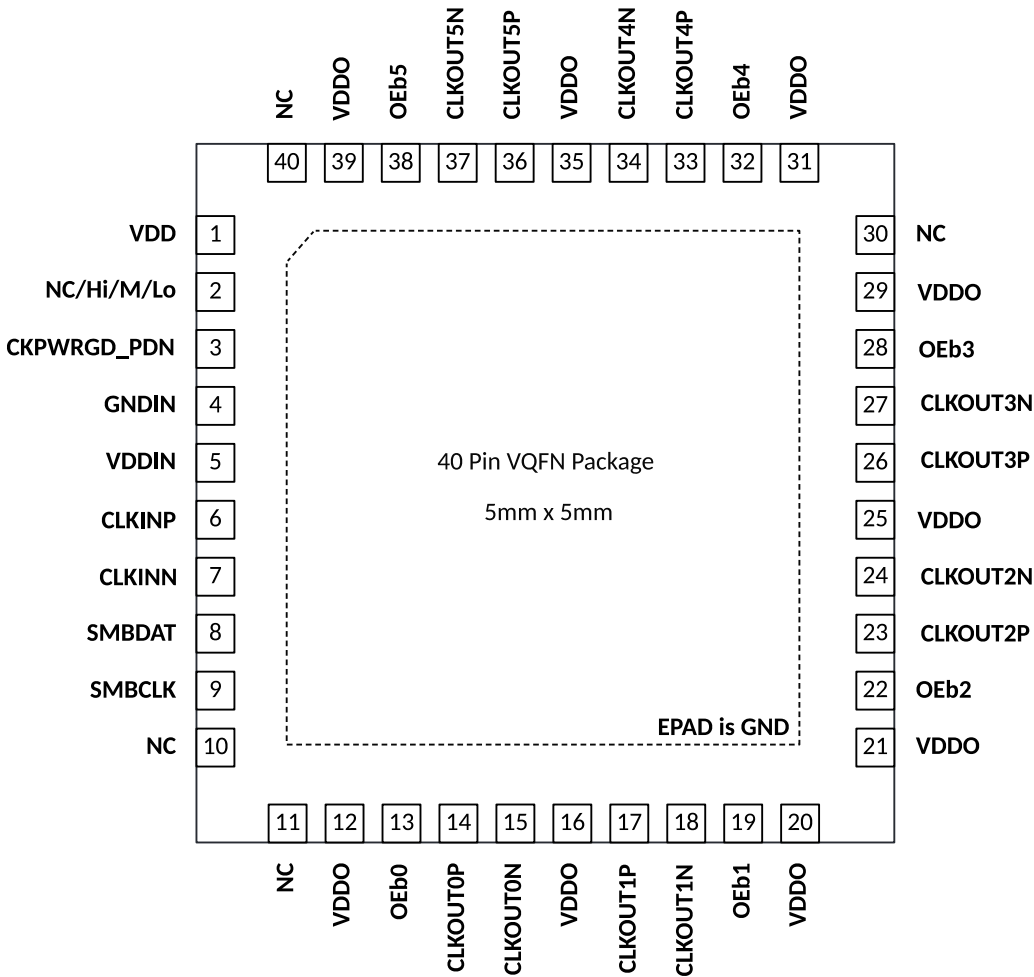


Figure 2. Pin Configuration

Table 10. Pin Description

Pin Name	Pin No.	I/O Type	Description
VDD	1	PWR	Analog VDD
CKPWRGD_PDN	3	I,PU,PDT	3.3 V Input notifies device to sample latched inputs and start up on first high assertion or exit Power Down Mode on subsequent assertions. Low enters Power Down Mode.
GNDIN	4	Ground	Differential Input clock (receiver) GND
VDDIN	5	PWR	3.3 V power for differential input clock (receiver). This VDD should be treated as an analog power rail and filtered appropriately.
CLKINP	6	I,PDT	0.8 V Differential True input
CLKINN	7	I,PDT	0.8 V Differential Complementary Input
SMBDAT	8	I/O, OD, PDT	Data pin of SMBUS circuitry, 3.3 V tolerant. Recommend to connect external 3.3Kohm pull up resistor for SMBUS operation.
SMBCLK	9	I, OD, PDT	Clock pin of SMBUS circuitry, 3.3 V tolerant. Recommend to connect external 3.3Kohm pull up resistor for SMBUS operation.
NC/Hi/M/Lo	2	N/A	This pin does not have any specific user function. NC or any static level will be acceptable.
NC	10, 11, 30, 40	N/A	No Connection. Recommended to be grounded.
VDDO	12, 16, 20, 21, 25, 29, 31, 35, 39	PWR	Power Supply for the Output Drivers, nominal 3.3 V

Pin Name	Pin No.	I/O Type	Description
OEB0	13	I, PD, PDT	Active low input for enabling Clock pair 0. This pin has an internal pull-down. 1 = disable outputs, 0 = enable outputs
CLKOUT0P	14	O	0.8 V differential true clock output
CLKOUT0N	15	O	0.8 V differential Complementary clock output
CLKOUT1P	17	O	0.8 V differential true clock output
CLKOUT1N	18	O	0.8 V differential Complementary clock output
OEB1	19	I, PD, PDT	Active low input for enabling Clock pair 1. 1 = disable outputs, 0 = enable outputs
CLKOUT2P	23	O	0.8 V differential true clock output
CLKOUT2N	24	O	0.8 V differential Complementary clock output
OEB2	22	I, PD, PDT	Active low input for enabling Clock pair 2. 1 = disable outputs, 0 = enable outputs
OEB3	28	I, PD, PDT	Active low input for enabling Clock pair 3. 1 = disable outputs, 0 = enable outputs
CLKOUT3P	26	O	0.8 V differential true clock output
CLKOUT3N	27	O	0.8 V differential Complementary clock output
CLKOUT4P	33	O	0.8 V differential true clock output
CLKOUT4N	34	O	0.8 V differential Complementary clock output
OEB4	32	I, PD, PDT	Active low input for enabling Clock pair 4. 1 = disable outputs, 0 = enable outputs
OEB5	38	I, PD, PDT	Active low input for enabling Clock pair 5. 1 = disable outputs, 0 = enable outputs
CLKOUT5P	36	O	0.8 V differential true clock output
CLKOUT5N	37	O	0.8 V differential Complementary clock output

Notes:

1. PU is weak internal Pull-up with 200 K Ω resistor.
2. PD is weak internal Pull-down with 200 K Ω resistor.
3. PDT (Power Down Tolerant) pins can be driven when the device is powered down without accidentally waking up the device.
4. Clock input pins are power down tolerant for voltage level < 1.8V on pins.
5. OD (Open Drain). It requires an external Pull-up on the board.
6. 'b' suffix (in OEB) indicates an active-low control.

Functional Description

Typical Application

Figure 3 shows a SiT92317 typical application. In this application, a clock generator provides a 100-MHz reference to the SiT92317 which then distributes that clock to PCIe endpoints. The clock generator may either be a

discrete clock generator, or it may be integrated in a larger component such as a Platform Controller Hub (PCH) or application processor.

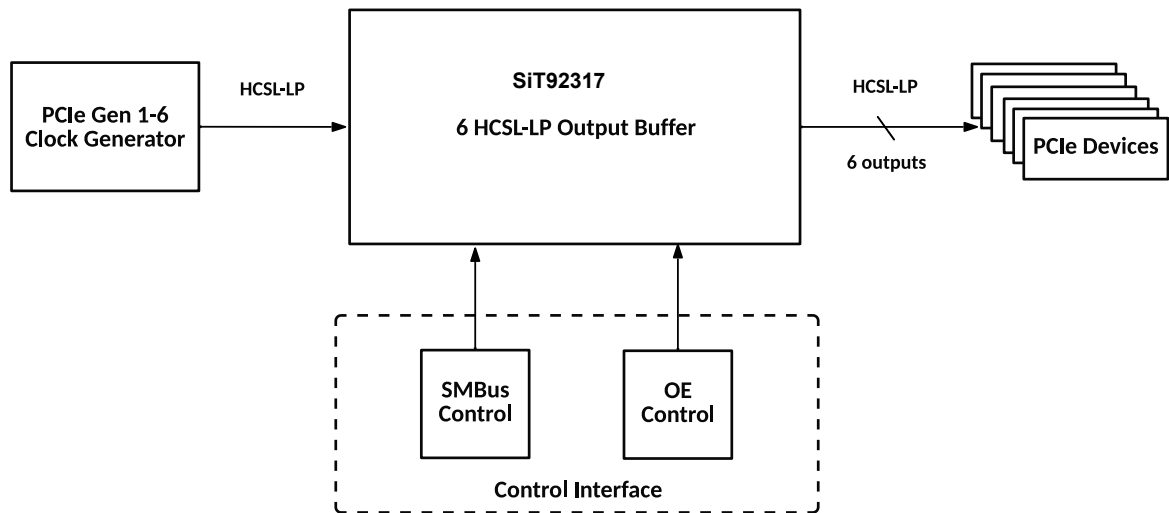


Figure 3. Typical Application Diagram

Parameter Measurement Information

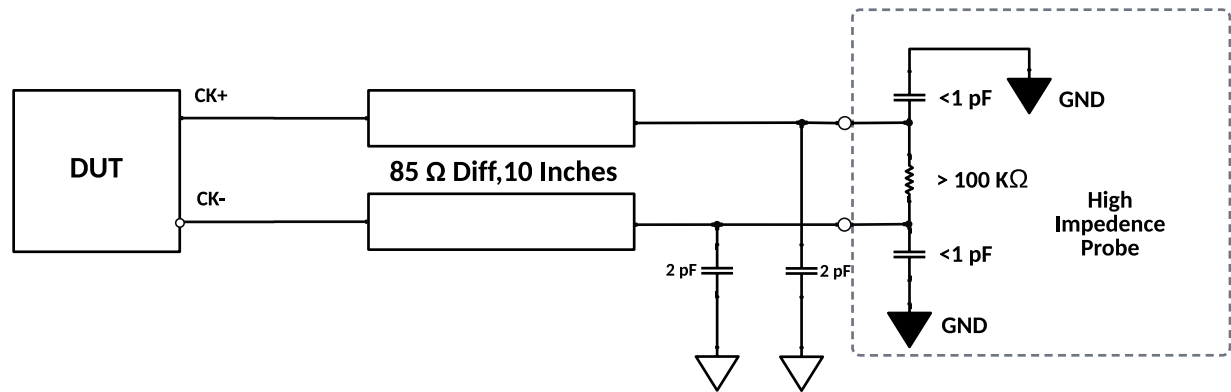


Figure 4. AC Test Mode

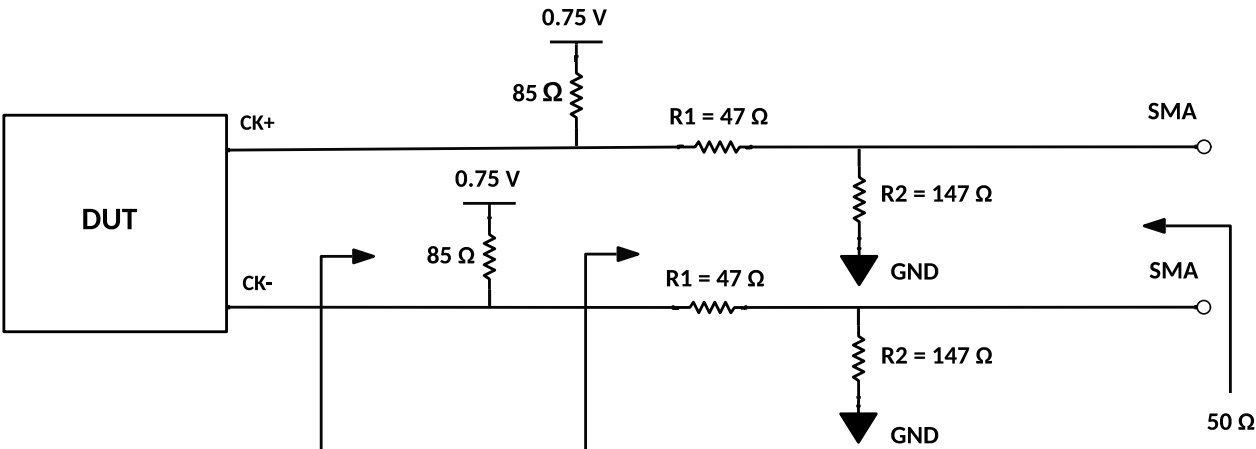


Figure 5. DC Simulation Mode

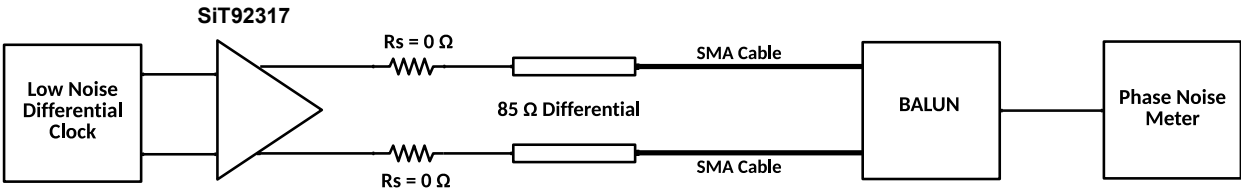


Figure 6. Phase Noise Measurement Setup

Table 11. Input vs Output States

Control Inputs	CLKIN	OEB[5:0] HARDWARE PINS AND SMBus CONTROL REGISTER BIT			CLKOUT[5:0]_P / CLKOUT[5:0]_N
		OE[5:0]b Pin	OUT_EN_CLK[5:0]	STOP_STATE_CONFIG_REG	
1	X	X	0	0	LOW/LOW
				1	HiZ/HiZ
				2	High/Low
				3	Low/High
		1	X	0	LOW/LOW
				1	HiZ/HiZ
				2	High/Low
				3	Low/High
0	X	X	X	X	Output Follow input
				0	LOW/LOW
				1	HiZ/HiZ
				2	High/Low
				3	Low/High

Power Good Assertion and De-assertion

Power Good (CKPWRGD_PDN) is asserted high and de-asserted low. De-assertion of CKPWRGD_PDN (pulling the signal low) is equivalent to indicating a powerdown condition. CKPWRGD_PDN (assertion) is used by the DB800Z to sample initial configurations such as SA selections.

After CKPWRGD_PDN has been asserted high for the first time, the pin becomes a PWRDNb (Power Down) pin that can be used to shut off all clocks cleanly and instruct the device to invoke power savings mode. PWRDNb is a completely asynchronous active low input.

When entering power savings mode, PWRDNb should be asserted low prior to shutting off the input clock or power to

ensure all clocks shut down in a glitch free manner. When PWRDNb is de-asserted high, all clocks will start and stop without any abnormal behavior and will meet all AC and DC parameters.

NOTE: The assertion and de-assertion of PWRDNb is asynchronous.

Warning: Disabling of the CLKIN input clock prior to the assertion of PWRDNb is an undefined mode and is not recommended. Operation in this mode may result in glitches.

Power Good De-Assertion

When PWRDNb is sampled low by two consecutive rising edges of CLKINN, all differential outputs must be held Tri-stated on the next CLKINN high to low transition.

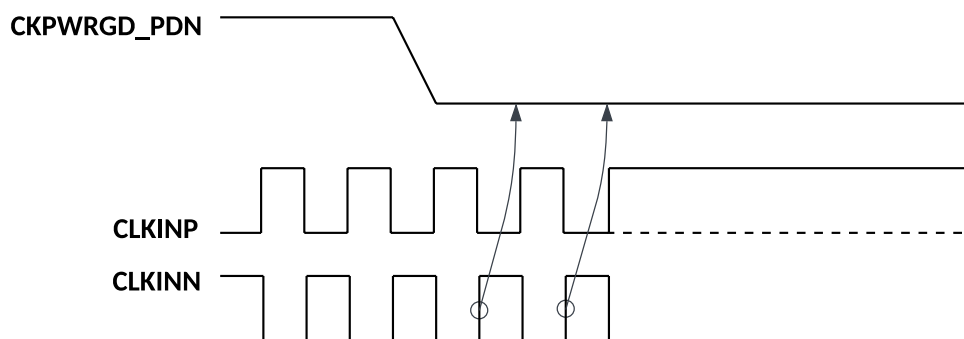


Figure 7. Power Good Assertion

Power Good Assertion

CKPWRGD_PDN must not be asserted to the clock buffer before VDD reaches VDD_{MIN}. Prior to VDD_{MIN} it is recommended to hold PWRGD low (less than 0.5 V).

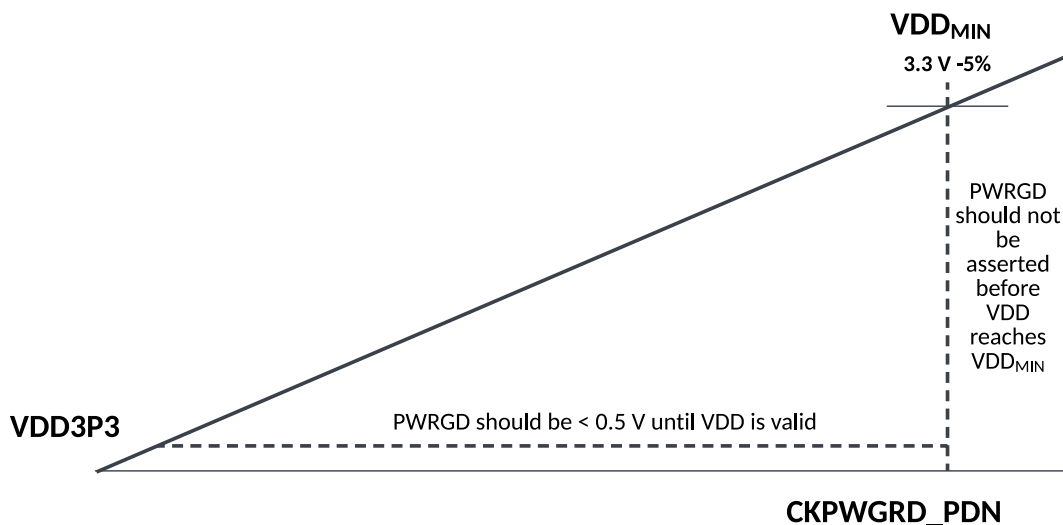


Figure 8. Power Good vs VDD3P3 relationship

The power-up latency in T_{STABLE} is to be less than 1.8 ms. This is the time from the valid CLKINx input and the assertion of the PWRGD signal until the output of the stable clocks from the buffer chip.

All differential outputs stopped in a Tri-state condition resulting from power down must be driven high in less than 300 μs of the PWRGD assertion to a voltage greater than 200 mV.

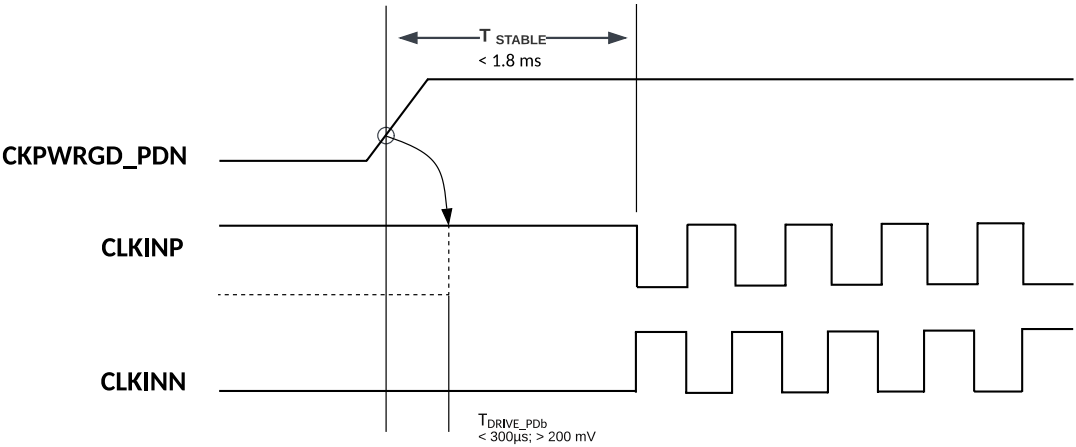


Figure 9. Power Good Assertion

Generic SMBus Description

The Figure 10 illustrates a generic SMBus sequence along with the description and functions of the constituent bytes elaborated in Table 12.

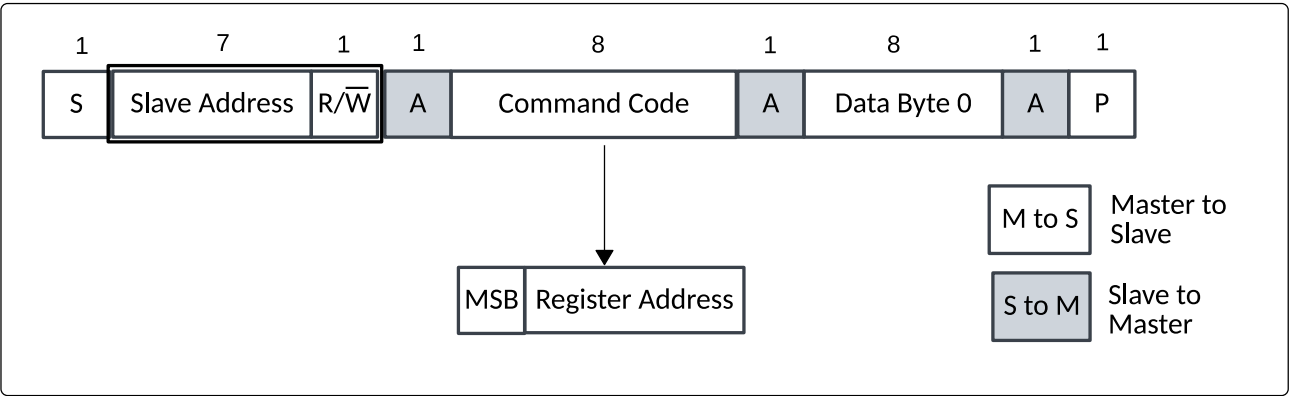


Figure 10. Generic SMBus Sequence

Table 12. SMBus Address Register Description

Description	Bit Range	Function
S	1	Start Condition
Sr	1	Repeated start condition
Slave Address	7 [7:1]	Address of the slave device.
R/W	1 [LSB]	1 = Read (Rd), 0 = Write (Wr)
A	1	1 = No-Acknowledgement (NA), 0 = Acknowledgement (A)
P	1	Stop condition
Command Code	1 [MSB]	1 = Byte read/write, 0 = Block read/write
	7 [6:0]	Register address

The register number should be specified when reading or writing a register in a SMBus slave device. While mentioning the register address, MSB must be SET for byte operation and must be RESET for block operations.

SMBus Byte: Read and Write Operations

Byte Read

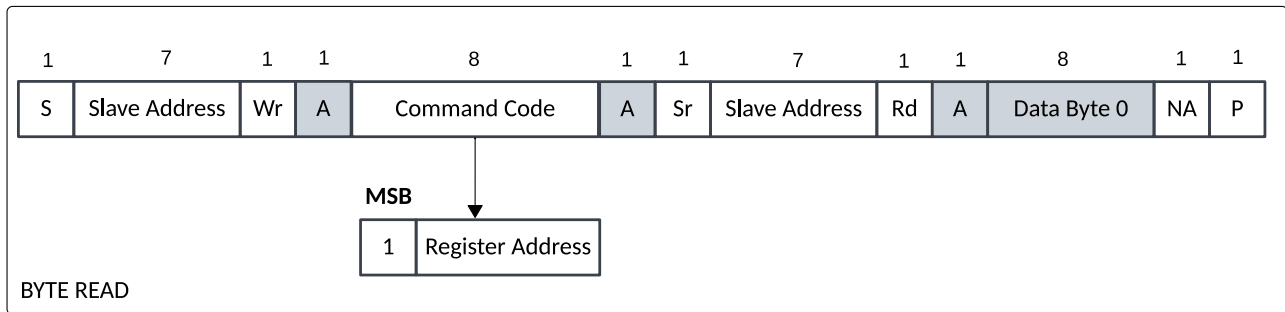


Figure 11. Byte Read Operation

- Master sends a start bit
- Master sends the slave address with LSB = Write
- Slave device will send acknowledgement (A)
- Master sends 8 bit register address (with MSB = 1 and byte read starting address [6:0])
- Slave device will send acknowledgement (A)
- Master sends a repeated start bit
- Master sends the slave address with LSB = Read
- Slave device will send acknowledgement (A)
- Slave device will send data byte
- Master will send not-acknowledgment (NA)
- Master will send a stop bit

Byte Write

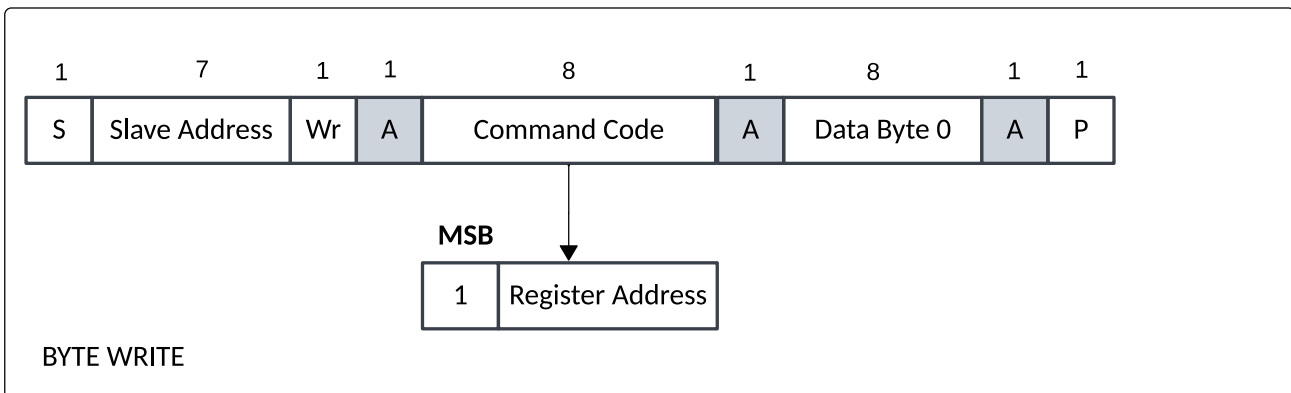


Figure 12. Byte Write Operation

- Master sends a start bit
- Master sends the slave address with LSB = Write
- Slave device will send acknowledgement (A)
- Master sends 8 bit register address (with MSB = 1 and byte write starting address [6:0])
- Slave device will send acknowledgement (A)
- Master sends data byte to be written
- Slave device will send acknowledgement (A)
- Master sends a stop bit

SMBus Block: Read and Write Operations

Block Read

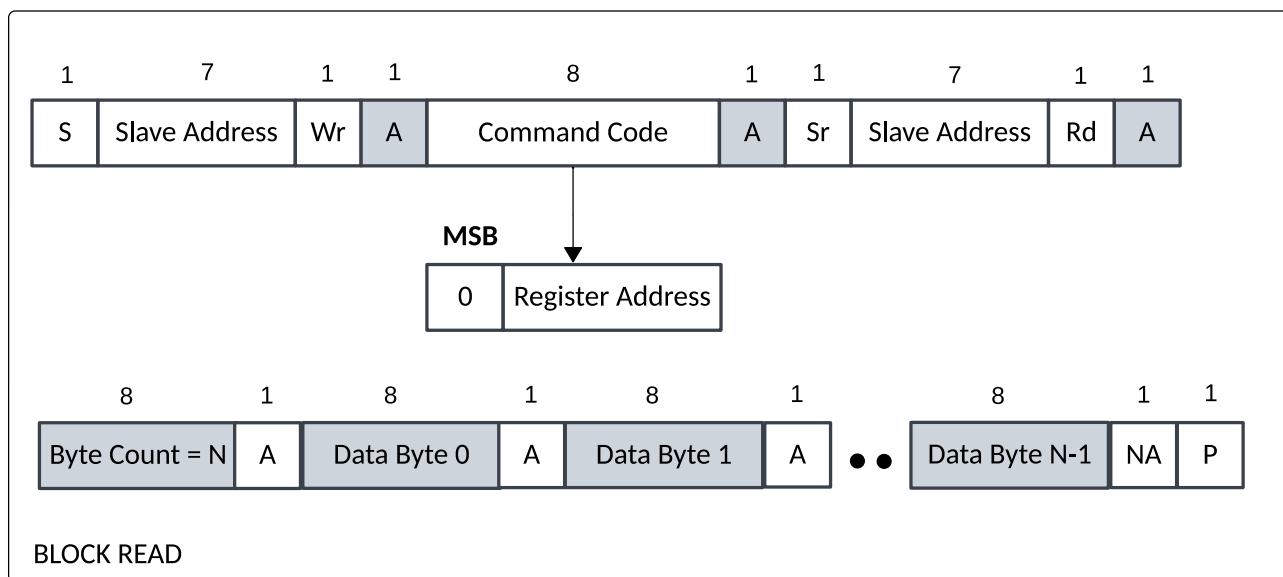


Figure 13. Block Read Operation

- Master sends a start bit
- Master sends the slave address with LSB = Write
- Slave device will send acknowledgement (A)
- Master sends 8 bit register address (with MSB = 0 and block read starting address [6:0])
- Slave device will send acknowledgement (A)
- Master sends a repeated start bit
- Master sends the slave address with LSB = Read
- Slave device will send acknowledgement (A)
- Slave device will send byte count N ($0 < N < 33$) that slave will transfer to the master
- Master sends acknowledgement (A)
- Slave device sends data bytes from data byte 0 to data byte N-1
- Master will send acknowledgement (A) for each data byte received (one at a time) except for the last data byte (N-1)
- Master will send not-acknowledgment (NA)
- Master will send a stop bit

Block Write

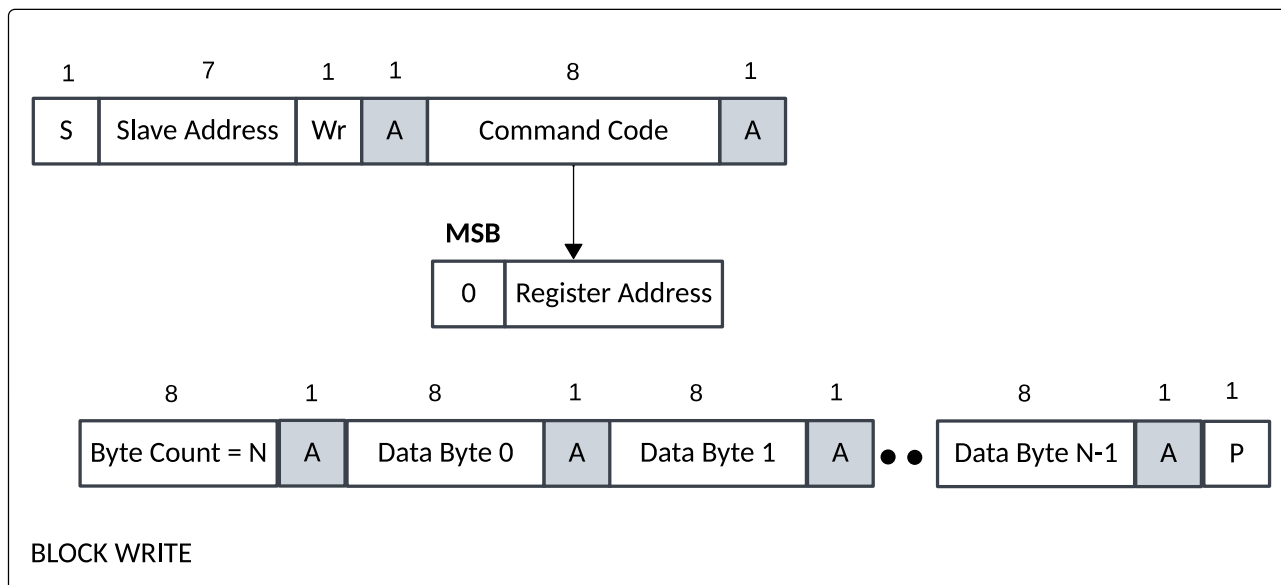


Figure 14. Block Write Operation

- Master sends a start bit
- Master sends the slave address with LSB = Write
- Slave device will send acknowledgement (A)
- Master sends 8 bit register address (with MSB = 0 and block write starting address [6:0])
- Slave device will send acknowledgement (A)
- Master sends byte count N ($0 < N < 33$) that master will transfer to the slave device
- Slave device will send acknowledgement (A)
- Master sends data bytes to be written from data byte 0 to data byte N-1
- Slave device will send acknowledgement (A) for each data byte received (one at a time)
- Master sends a stop bit

Note: For cases where an SMBus bus transaction concludes with a write operation, ensure that the SMBus master does not toggle the clock inadvertently between the STOP and the next START condition to prevent unintended write operations. For cases where inadvertent clocks can occur between the STOP and the next START condition, it is recommended to conclude the SMBus transaction with a read operation.

SMBus Address

The device has a default address of 0x6c (7-bit address)

Register Address

Table 13. Register Map Address

Register Address	Bit Range	Register name	Default	Type	Bit Name	Description and Function
0x00	7:0	RCR1	0	RO	RESERVED	
0x01	7	OE_CTRL 1	0	RW	RESERVED	1: Output Enable 0: STOP_STATE Mode
	6		1		DIF3_ENABLE	
	5		1		DIF2_ENABLE	
	4		0		RESERVED	
	3		0		RESERVED	
	2		1		DIF1_ENABLE	
	1		1		DIF0_ENABLE	
	0		0		RESERVED	
	0		0		RESERVED	
0x02	7:3	OE_CTRL 2	0	RW	RESERVED	1: Output Enable 0: STOP_STATE Mode
	2		1		DIF5_ENABLE	
	1		1		DIF4_ENABLE	
	0		0		RESERVED	
0x03	7:0	RCR2	0	RO	RESERVED	
0x04	7:0	RCR3	0	RO	RESERVED	
0x05	7:4	VEN_REV_ID	0xa2	RO	REVISION_ID	revA : 0xa
	3:0				VENDOR_ID	SiTime product: 0x2
0x06	7:0	DEV_ID	0	RO	DEVICE_ID	Device ID bits[7:0] map to register bits[7:0] directly. Product Code
0x07	7:5	BYTES_READ_COUNT	0	RO	RESERVED	
	4:0		8	RW	BYTES_READ_COUNT_VALUE	Writing to this register configures how many bytes will be read back on a block
0x10	7	OE_PIN_READ_BACK	0	RO	RESERVED	Output Enable Pin read Back
	6		0		RB_OE5	
	5		0		RB_OE4	
	4		0		RB_OE3	
	3		0		RB_OE2	
	2		0		RESERVED	
	1		0		RB_OE1	
	0		0		RB_OE0	
	0		0		RB_OE0	
0x14	7:2	STOP_STATE_CONFIG_REG	0	RO	RESERVED	
	1:0		0	RW	STOP_STATE	00 = Low/Low 01 = Hiz/Hiz 10 = High/Low 11 Low/High
0x15	7:2	SLEW_CTRL_REG	0x01	RO	RESERVED	
	1:0			RW	SLEW_RATE	Refer Table 14 Default slew rate is 3.5 V/ns
0x16	7:4	AMP_CTRL_REG	0	RO	RESERVED	
	3:0		Refer note[1]	RW	OUTPUT_AMPLITUDE	Default Amplitude is 0.8 Vpeak typical. Step size is 25 mV typical and monotonically decreasing from code 0 to 15

Note:

- For changing the default amplitude value, Readback the amplitude code and apply the relative change in code.

Table 14. Default Slew Value

Slew Code Reg. 0x15[1:0]	Typical Slewrate Value (V/ns) @ for 0.8V swing (measured on 10 inch T-line with 2pf load)
0	3.8
1	2.9
2	2.4
3	2

Package Dimensions and Patterns

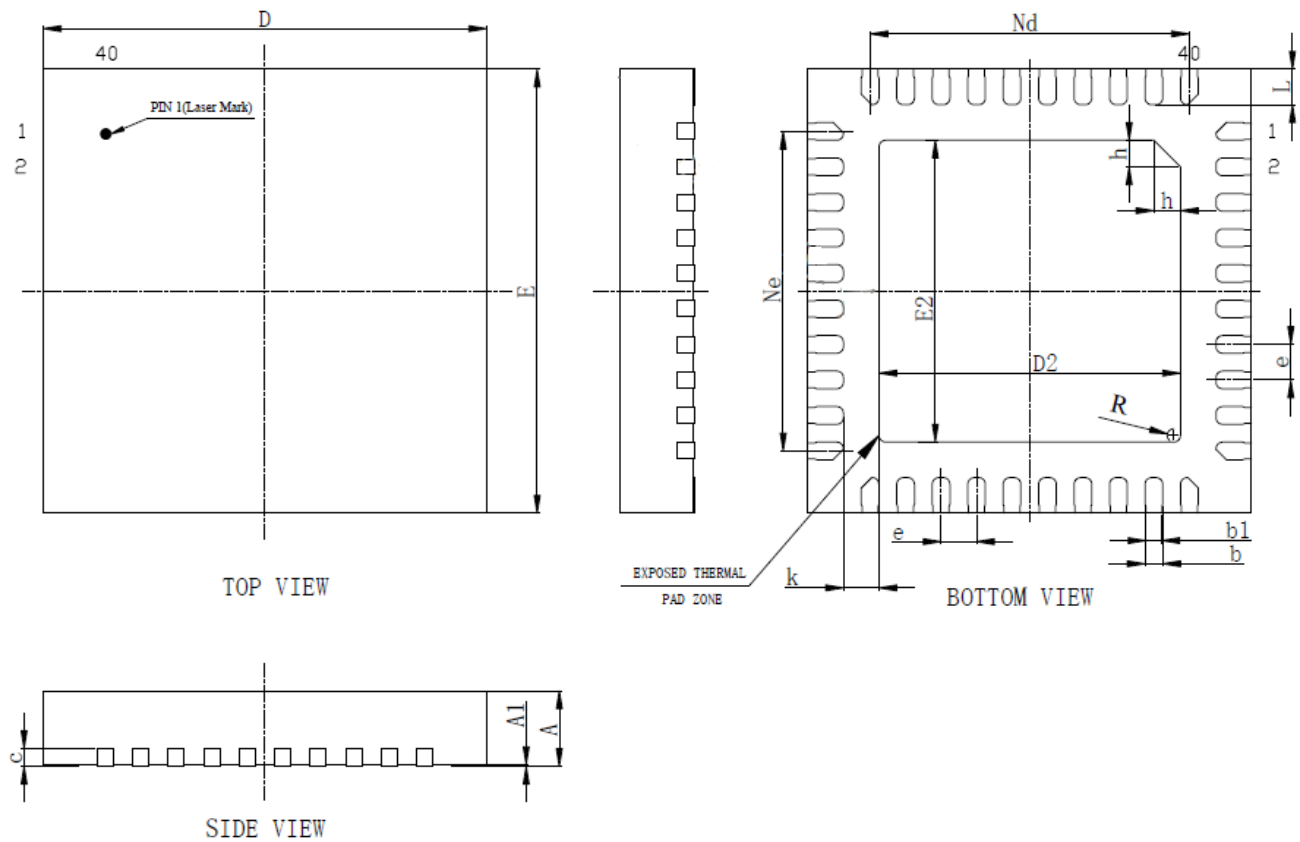


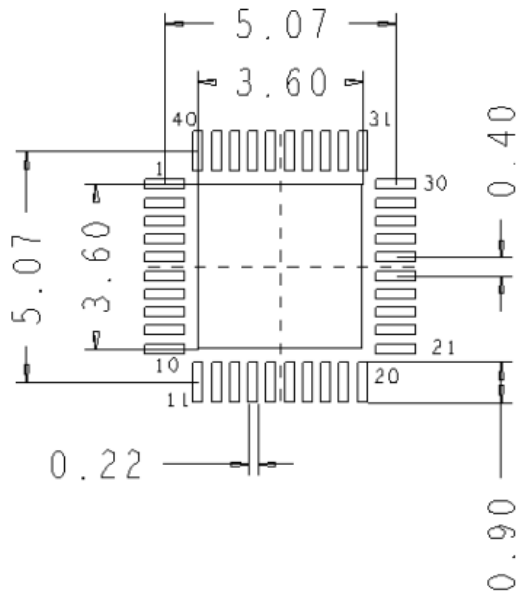
Figure 15. Package Diagram SiT92317 40 pin VQFN

Symbol	Millimeter		
	MIN	NOM	MAX
A	0.80	0.85	0.95
A1	0	0.02	0.05
b	0.15	0.20	0.25
b1	0.18 REF		
c	0.18 REF		
D	4.90	5.00	5.10
D2	3.35	3.40	3.45
e	0.40 BSC		
Ne	3.60 BSC		
Nd	3.60 BSC		
E	4.90	5.00	5.10
E2	3.35	3.40	3.45
L	0.35	0.40	0.45
h	0.25	0.30	0.35
R	0.075 REF		
K	0.35	0.40	0.45

Notes: All measurements are in millimeters (mm).

Land Pattern and Solder Paste Design

LAND PATTERN EXAMPLE



SOLDER PASTE EXAMPLE

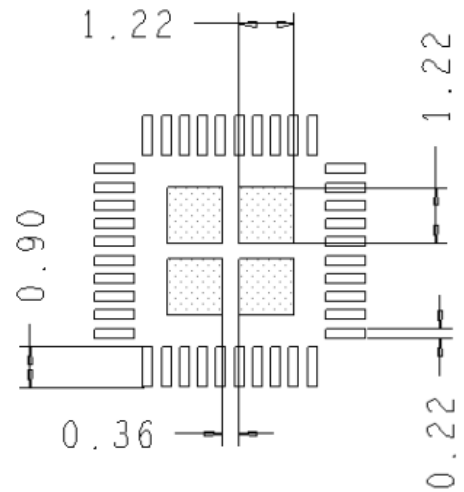


Figure 16. SiT92317 Land Pattern Design

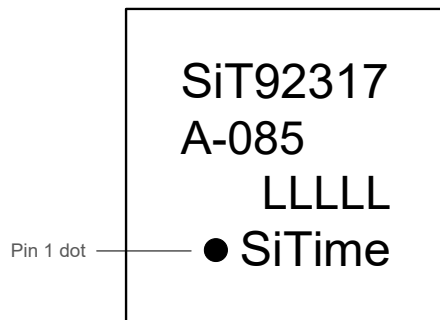
General Notes

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This Land Pattern Design is based on the IPC-7351 guidelines.
3. All dimensions shown are at Maximum Material Condition (MMC). Least Material Condition is calculated based on a fabrication allowance of 0.05 mm.

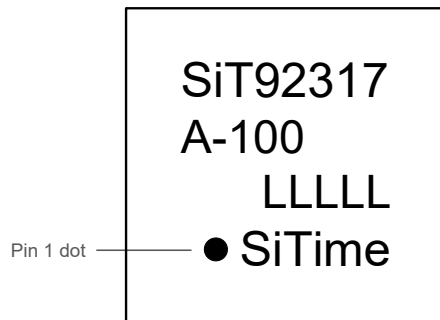
SOLDER MASK DESIGN

1. All metal pads are to be non-solder mask defined (NSMD).

Top Marking



Line 1: "SiT92317" SiTime part number
Line 2: "A-085" represent revision A and 85 Ohm impedance
Line 3: "LLLLL" Lot code from SiTime
Line 4: Pin 1 dot and "SiTime" logo



Line 1: "SiT92317" SiTime part number
Line 2: "A-100" represent revision A and 100 Ohm impedance
Line 3: "LLLLL" Lot code from SiTime
Line 4: Pin 1 dot and "SiTime" logo

Revision History

Table 15. Revision History

Revisions	Release Date	Change Summary
0.5	11-Dec-2023	Initial Release
0.52	4-Apr-2025	Ordering Code for Packaging updated with 4Ku/reel code "P" and 500u/reel code "N" Added Top Marking section
0.53	3-Oct-2025	Update PCIe Gen1-7 instead of 1-6 Added 100 Ohm Termination option: 1 st page Features and Ordering Information
0.6	21-Jan-2026	Updated Ordering Information and Top Marking section with 85 and 100 Ω options
0.7	23-Feb-2026	Correct descriptions on the Table 9 Pin Description
0.77	13-April-2026	Add SMBUS description, timing chart, remove top marking page
0.9	22-Jul-2026	Updated following section - Electrical specs max value updated - Top marking and land pattern updated - Typo in register map corrected
0.91	28-Jul-2026	Typical Swing (Vpeak) updated for output
1.0	3-Sep-2026	Top marking updated Disclaimer updated Production version
1.01	10-Sep-2026	Top marking updated Ordering Information updated

SiTime Corporation, 5451 Patrick Henry Drive, Santa Clara, CA 95054, USA | **Phone:** +1-408-328-4400 | **Fax:** +1-408-328-4439

© SiTime Corporation 2023-2026. The information contained herein is subject to change at any time without notice. SiTime assumes no responsibility or liability for any loss, damage or defect of a Product which is caused in whole or in part by (i) use of any circuitry other than circuitry embodied in a SiTime product, (ii) misuse or abuse including static discharge, neglect or accident, (iii) unauthorized modification or repairs which have been soldered or altered during assembly and are not capable of being tested by SiTime under its normal test conditions, or (iv) improper installation, storage, handling, warehousing or transportation, or (v) being subjected to unusual physical, thermal, or electrical stress.

Disclaimer: SiTime makes no warranty of any kind, express or implied, with regard to this material, and specifically disclaims any and all express or implied warranties, either in fact or by operation of law, statutory or otherwise, including the implied warranties of merchantability and fitness for use or a particular purpose, and any implied warranty arising from course of dealing or usage of trade, as well as any common-law duties relating to accuracy or lack of negligence, with respect to this material, any SiTime product and any product documentation.

HIGH RISK USE. BUYER UNDERSTANDS AND ACKNOWLEDGES THAT SELLER'S PRODUCTS ARE NOT DESIGNED OR INTENDED FOR USE AS COMPONENTS IN NUCLEAR FACILITIES. ADDITIONALLY, BUYER UNDERSTANDS AND ACKNOWLEDGES THAT, EXCEPT AS SET FORTH IN THE PARAGRAPH IMMEDIATELY BELOW, SELLER'S PRODUCTS ARE NOT DESIGNED OR INTENDED FOR USE IN LIFE OR CRITICAL SUPPORT DEVICES, DEFENSE, AEROSPACE, NAVIGATION, MEDICAL, OR OTHER MISSION-CRITICAL APPLICATIONS OR COMPONENTS WHERE HUMAN LIFE MAY BE AT STAKE. SELLER EXPRESSLY DISCLAIMS THE WARRANTIES SET FORTH ABOVE FOR ANY PRODUCT USES INCONSISTENT WITH THE TERMS OF THIS SECTION, AND BUYER SHALL DEFEND, INDEMNIFY AND HOLD SELLER HARMLESS FOR ALL LOSS, DAMAGE, EXPENSE OR LIABILITY IN CONNECTION WITH SUCH USES.

ENDURA™ RUGGEDIZED PRODUCTS. ONLY SELLER'S ENDURA™ RUGGEDIZED PRODUCTS SHOULD BE CONSIDERED FOR LIFE OR CRITICAL SUPPORT DEVICES, DEFENSE, AEROSPACE, NAVIGATION, MEDICAL, OR OTHER MISSION-CRITICAL APPLICATIONS OR COMPONENTS WHERE HUMAN LIFE MAY BE INVOLVED OR AT STAKE.

SiTime owns all rights, title and interest to the intellectual property related to SiTime's products, including any software, firmware, copyright, patent, or trademark. The sale of SiTime products does not convey or imply any license under patent or other rights. SiTime retains the copyright and trademark rights in all documents, catalogs and plans supplied pursuant to or ancillary to the sale of products or services by SiTime. Unless otherwise agreed to in writing by SiTime, any reproduction, modification, translation, compilation, or representation of this material shall be strictly prohibited.